

# **Technical data sheet**

MP/27BUS

Communicative damper actuator for adjusting dampers in technical building installations

- Air damper size up to approx. 2 m<sup>2</sup>
- Torque motor 10 Nm
- Nominal voltage AC/DC 24 V
- Control modulating, communicative 2...10 V variable
- Position feedback 2...10 V variable
- Communication via Belimo MP-Bus
- Conversion of sensor signals

**Technical data** 



Picture may differ from product

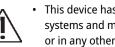
Electrical data	Nominal voltage	AC/DC 24 V	
	Nominal voltage frequency	50/60 Hz	
	Nominal voltage range	AC 19.228.8 V / DC 21.628.8 V	
	Power consumption in operation	3.5 W	
	Power consumption in rest position	1.4 W	
	Power consumption for wire sizing	6 VA	
	Connection supply / control	Cable 1 m, 4x 0.75 mm <sup>2</sup>	
	Parallel operation	Yes (note the performance data)	
Data bus communication	Communicative control	MP-Bus	
	Number of nodes	MP-Bus max. 8	
Functional data	Torque motor	10 Nm	
	Torque variable	25%, 50%, 75% reduced	
	Operating range Y	210 V	
	Input impedance	100 kΩ	
	Operating range Y variable	Start point 0.530 V	
		End point 2.532 V	
	Operating modes optional	Open/close	
		3-point (AC only)	
		Modulating (DC 032 V)	
	Position feedback U	210 V	
	Position feedback U note	Max. 0.5 mA	
	Position feedback U variable	Start point 0.58 V	
	Desition accuracy	End point 2.510 V ±5%	
	Position accuracy		
	Direction of motion motor	selectable with switch 0/1	
	Direction of motion variable	electronically reversible	
	Direction of motion note	Y = 0 V: At switch position 0 (ccw rotation) 1 (cw rotation)	
	Manual override	with push-button, can be locked	
	Angle of rotation	Max. 95°	
	Angle of rotation note	can be limited on both sides with adjustable	
		mechanical end stops	
	Running time motor	150 s / 90°	
	Running time motor variable	43173 s	
	Sound power level, motor	35 dB(A)	



Technical data sheet

Functional data	Adaptation setting range	manual		
	Adaptation setting range variable	No action Adaptation when switched on Adaptation after pushing the manual override button MAX (maximum position) = 100% MIN (minimum position) = 0% ZS (intermediate position, AC only) = 50% MAX = (MIN + 32%)100% MIN = 0%(MAX – 32%) ZS = MINMAX		
	Override control			
	Override control variable			
	Mechanical interface	Universal shaft clamp 826.7 mm		
	Position indication	Mechanical, pluggable		
Safety data	Protection class IEC/EN	III, Safety Extra-Low Voltage (SELV)		
	Power source UL	Class 2 Supply		
	Degree of protection IEC/EN	IP54		
	Degree of protection NEMA/UL	NEMA 2		
	Housing	UL Enclosure Type 2		
	EMC	CE according to 2014/30/EU		
	Certification IEC/EN	IEC/EN 60730-1 and IEC/EN 60730-2-14		
	UL Approval	cULus according to UL60730-1A, UL60730-2-14 and CAN/CSA E60730-1 The UL marking on the actuator depends on the production site, the device is UL-compliant in any case		
	Hygiene test	According to VDI 6022 Part 1 / SWKI VA 104-01, cleanable and disinfectable, low emission		
	Type of action	Type 1		
	Rated impulse voltage supply / control	0.8 kV		
	Pollution degree	3		
	Ambient humidity	Max. 95% RH, non-condensing		
	Ambient temperature	-3050°C [-22122°F]		
	Storage temperature	-4080°C [-40176°F]		
	Servicing	maintenance-free		
Weight	Weight	0.77 kg		

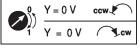
#### Safety notes



- This device has been designed for use in stationary heating, ventilation and air-conditioning systems and must not be used outside the specified field of application, especially in aircraft or in any other airborne means of transport.
- Outdoor application: only possible in case that no (sea) water, snow, ice, insolation or aggressive gases interfere directly with the device and that it is ensured that the ambient conditions remain within the thresholds according to the data sheet at any time.
- Only authorised specialists may carry out installation. All applicable legal or institutional installation regulations must be complied with during installation.
- The device may only be opened at the manufacturer's site. It does not contain any parts that can be replaced or repaired by the user.
- Cables must not be removed from the device.
- To calculate the torque required, the specifications supplied by the damper manufacturers concerning the cross-section and the design, as well as the installation situation and the ventilation conditions must be observed.
- · The device contains electrical and electronic components and must not be disposed of as household refuse. All locally valid regulations and requirements must be observed.

#### **Product features**

Operating mode	Conventional operation:
	The actuator is controlled with a standard control signal of DC 010 V (note the operating range) and drives to the position defined by the control signal. The measuring voltage U serves for the electrical display of the actuator position 0.5100% and as control signal for other actuators.
	Operation on Bus:
	The actuator receives its digital control signal from the higher level controller via the MP-Bus and drives to the position defined. Connection U serves as communication interface and does not supply an analogue measuring voltage.
Converter for sensors	Connection option for a sensor (passive or active sensor or switching contact). The MP actuator serves as an analogue/digital converter for the transmission of the sensor signal via MP-Bus to the higher level system.
Configurable device	The factory settings cover the most common applications. Single parameters can be modified with Belimo Assistant 2 or ZTH EU.
Simple direct mounting	Simple direct mounting on the damper shaft with a universal shaft clamp, supplied with an an anti-rotation mechanism to prevent the actuator from rotating.
Manual override	Manual override with push-button possible (the gear train is disengaged for as long as the button is pressed or remains locked).
Adjustable angle of rotation	Adjustable angle of rotation with mechanical end stops.
High functional reliability	The actuator is overload protected, requires no limit switches and automatically stops when the end stop is reached.
Home position	The first time the supply voltage is switched on, i.e. at the time of commissioning, the actuator carries out a synchronisation. The synchronisation is in the home position (0%).
	The actuator then moves into the position defined by the control signal.







Adaptation and synchronisation	An adaptation can be triggered manually by pressing the "Adaptation" button or with Belimo Assistant 2. Both mechanical end stops are detected during the adaptation (entire setting range).			
	Automatic synchronisation after pressing the manual override button is c synchronisation is in the home position (0%).	onfigured. The		
	The actuator then moves into the position defined by the control signal.			
	A range of settings can be made using Belimo Assistant 2.			
Accessories				
Tools	Description	Туре		
	Service tool, with ZIP-USB function, for configurable and communicative Belimo actuators, VAV controller and HVAC performance devices	ZTH EU		
	Service tool for wired and wireless setup, on-site operation and troubleshooting.	Belimo Assistant 2		
	Adapter for Service-Tool ZTH	MFT-C		
	Connecting cable 5 m, A: RJ11 6/4 ZTH EU, B: 6-pin for connection to service socket	ZK1-GEN		
	Connecting cable 5 m, A: RJ11 6/4 ZTH EU, B: free wire end for connection to MP/PP terminal	ZK2-GEN		
Electrical accessories	Description	Туре		
	Auxiliary switch 1x SPDT add-on	S1A		
	Auxiliary switch 2x SPDT add-on	S2A		
	Feedback potentiometer 140 $\Omega$ add-on	P140A		
	Feedback potentiometer 1 k $\Omega$ add-on	P1000A		
	Feedback potentiometer 10 k $\Omega$ add-on	P10000A		
	Signal converter voltage/current 100 k $\Omega$ 420 mA, Supply AC/DC 24 V	Z-UIC		
	Positioner for wall mounting	SGA24		
	Positioner for built-in mounting	SGE24		
	Positioner for front-panel mounting	SGF24		
	Positioner for wall mounting	CRP24-B1		
	MP-Bus power supply for MP actuators	ZN230-24MP		
Gateways	Description	Туре		
	Gateway MP to BACnet MS/TP	UK24BAC		
	Gateway MP to Modbus RTU	UK24MOD		
Mechanical accessories	Description	Туре		
	Actuator arm for standard shaft clamp (one-sided)	AH-25		
	Shaft extension 240 mm ø20 mm for damper shaft ø822.7 mm	AV8-25		
	Ball joint suitable for damper crank arm KH8	KG8		
	Ball joint suitable for damper crank arm KH8 / KH10	KG10A		
	Damper crank arm Slot width 8.2 mm, clamping range ø1018 mm	KH8		
	Shaft clamp one-sided, clamping range ø826 mm with insert, Multipack 20 pcs.	K-ENMA		
	Shaft clamp one-sided, clamping range ø826 mm, Multipack 20 pcs.	K-ENSA		
	Shaft clamp reversible, clamping range ø820 mm	K-NA		
	Form fit insert 8x8 mm, Multipack 20 pcs.	ZF8-NMA		
	Form fit insert 10x10 mm, Multipack 20 pcs.	ZF10-NSA		
	Form fit insert 12x12 mm, Multipack 20 pcs.	ZF12-NSA		
	Form fit insert 15x15 mm, Multipack 20 pcs.	ZF15-NSA		
	Form fit insert 16x16 mm, Multipack 20 pcs.	ZF16-NSA		
	Mounting kit for linkage operation for flat installation	ZG-NMA		
	Anti-rotation mechanism 180 mm, Multipack 20 pcs.	Z-ARS180		
	Baseplate extension for NMA to NM	Z-NMA		
	Position indicator, Multipack 20 pcs.	Z-PI		



# **Electrical installation**



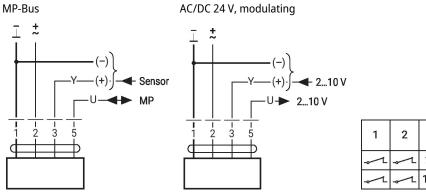
Supply from isolating transformer.

Parallel connection of other actuators possible. Observe the performance data.

Wire colours:

- 1 = black
- 2 = red
- 3 = white

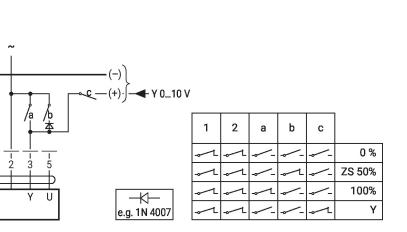
5 = orange

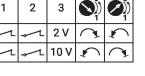


#### **Further electrical installations**

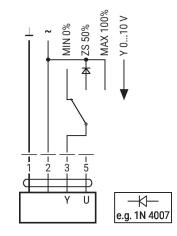
#### Functions with basic values (conventional mode)

Override control with AC 24 V with relay contacts





Override control with AC 24 V with rotary switch

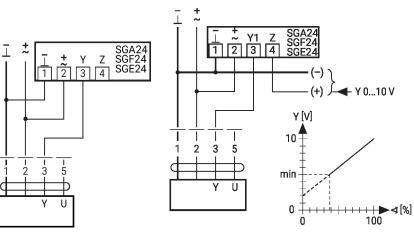




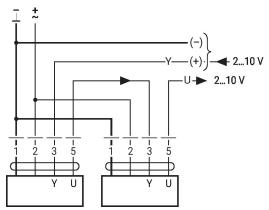
#### Functions with basic values (conventional mode)

Control remotely 0...100% with Minimum li positioner SG.

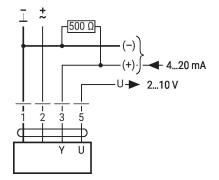
Minimum limit with positioner SG..



Primary/secondary operation (position-dependent)



Control with 4...20 mA via external resistor



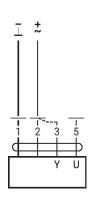
### Caution:

The operating range must be set to DC 2...10 V. The 500 Ohm resistor converts the 4...20 mA current signal to a voltage signal DC 2...10 V.



#### Functions with basic values (conventional mode)

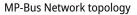
#### **Functional check**

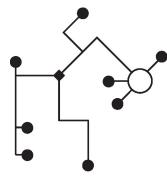


### Procedure

1. Connect 24 V to connections 1 and 2 2. Disconnect connection 3: - With direction of rotation 0: Actuator rotates to the left - With direction of rotation 1: Actuator rotates to the right 3. Short-circuit connections 2 and 3: - Actuator runs in opposite direction

MP-Bus





#### There are no restrictions for the network topology (star, ring, tree or mixed forms are permitted). Supply and communication in

one and the same 3-wire cable • no shielding or twisting

necessary • no terminating resistors required

• Supply AC/DC 24 V

Resolution 30 mV

0...32 V)

• Output signal 0...10 V (max.

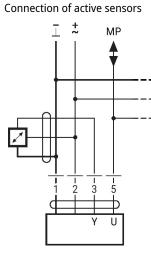


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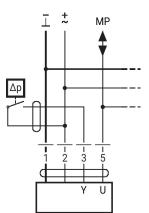
Connection on the MP-Bus

MP

Max. 8 MP-Bus nodes



Connection of external switching contact



 Switching current 16 mA @ 24 ٧

• Start point of the operating range must be configured on the MP actuator as ≥0.5 V

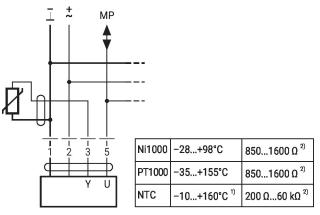


**Technical data sheet** 

# Further electrical installations

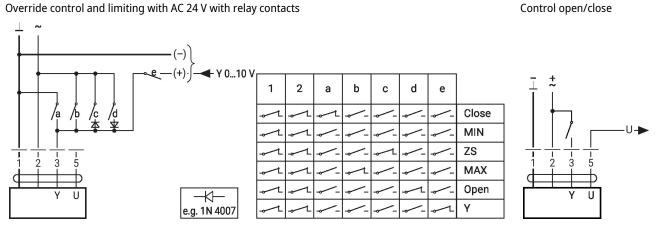
# MP-Bus

Connection of passive sensors



#### Functions with specific parameters (configuration necessary)

Override control and limiting with AC 24 V with relay contacts



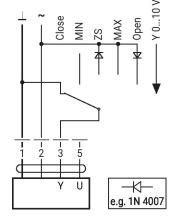
#### Override control and limiting with AC 24 V with rotary switch

# Control 3-point with AC 24 V

1) Depending on the type 2) Resolution 1 Ohm

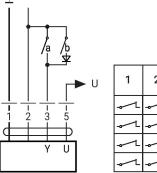
value is recommended

Compensation of the measured



#### Caution:

The "Close" function is only guaranteed if the start point of the operating range is defined as min. 0.5 V.



K e.g. 1N 4007					
1	2	3 (a)	3 (b)		
2	<b>~</b> ∟	<b>~</b> ∟	-~~	$\mathbf{r}$	$\widehat{}$
2	-~~L	~~	-~~L	$\mathbf{r}$	$\widehat{}$
~	-~~L	-~-	-~	stop	stop
~~	-∕-	-~	-~	3	$\mathbf{\hat{\mathbf{A}}}$



# Operating controls and indicators

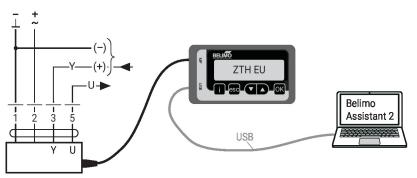
	1	Direction of rota	
Adaption -		Switch over:	Direction of rotation changes
Address → (2)	2	Push-button and	l LED display green
Status		Off:	No power supply or malfunction
4		On:	In operation
		Press button:	Triggers angle of rotation adaptation, followed by standard mode
6	3	Push-button and	l LED display yellow
		Off:	Standard mode
		On:	Adaptation or synchronisation process active
		Flickering:	MP-Bus communication active
		Flashing:	Request for addressing from MP client
		Press button:	Confirmation of the addressing
	4	Manual override	button
		Press button:	Gear train disengages, motor stops, manual override possible
		Release button:	Gear train engages, synchronisation starts, followed by standard mode
	6	<b>Service plug</b> For connecting c	onfiguration and service tools
		Check power su	pply connection
		2 Off and 3	On Possible wiring error in power supply
)			
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Service

#### Wired connection

tion The device can be configured by ZTH EU via the service socket. For an extended configuration, Belimo Assistant 2 can be connected.

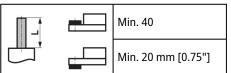
#### Connection ZTH EU / Belimo Assistant 2





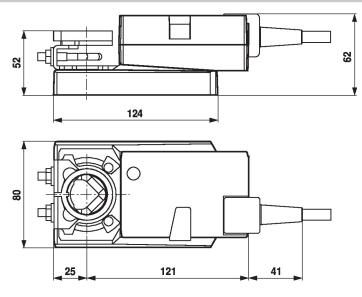
### Dimensions

### Spindle length



# Clamping range

	O		$\mathbf{A}$
	826.7	≥8	≤26.7
*	820	≥8	≤20



\*Option: Shaft clamp mounted below (accessories K-NA needed)

#### **Further documentation**

- Overview MP Cooperation Partners
- Tool connections
- Introduction to MP-Bus Technology
- Quick Guide Belimo Assistant 2

# **Application notes**

• For digital control of actuators in VAV applications patent EP 3163399 must be considered.